The following algorithm accepts a vector of coefficients and an x value and returns the corresponding polynomial evaluated at x.

Identify the component which represents the input size and give the Big-oh notation for the time complexity of this algorithm. In order to receive partial credit, be sure to explain your reasoning.

Show that the following equality is incorrect:

$$10n^2 + 9 = O(n)$$

CS-285-1,4

Name:

The following algorithm is an alternative version of the Chain<T>::insert() function. Determine whether it is a valid substitute for the one given in class. If not, indicate the input conditions for which it would fail.

```
\texttt{template} < \texttt{class} \ T >
   void Chain<T>::insert(unsigned int k, const T& val)
2
     if(k \le size())
4
       6
          newLnk->next = first;
          first = newLnk;
8
        } else {
  Link<T> * itr = first;
10
          while(--k>0) {
            itr = itr->next;
12
14
          newLnk->next = itr->next;
          itr \rightarrow next = newLnk;
16
18
```

Recall the Chain<T> class discussed in lecture:

Write the class generated by the precompiler the first time the precompiler encounters the following:

Chain

cbool
aChainOfBools;

Briefly describe the role of a *stub* in program testing and give an example.

Briefly describe the role of an *invariant* in establishing confidence in program correctness.

What characteristics make an *adaptor* class different from a standard class?

Recall from lecture the generalized generic algorithm accumulate():

What type of iterator is required by this generic algorithm.

Describe the concept of **folding** as it pertains to hash functions. Give an example.

Suppose you are asked to place all of the buildings in Milwaukee into a hash table of size 1010.

Which hash function would be best:

- 1. (Number of bricks)% 1003
- 2. (Number of windows)% 2000
- 3. (Numerical part of street address)% 1010
- 4. (Sum of all the ASCII values of the street address)% 1003
- 5. (Number of broken ceiling tiles)% 1010

For full credit, justify your answer.

Recall that the BinaryNode class has three protected data members (BinaryNode<T>* left, BinaryNode<T>* right, and T data) and the BinaryTree class has one protected data member (BinaryNode<T>* root). Suppose you are given the following find() member function:

```
template <class T>
bool BinaryTree<T>::find(const T& x) const
{

BinaryNode<T>* found = find(root, x);
    if(found==0)

return false;
    return true;
}
```

Finish writing the recursive find() member function called in line four of the above function. You may assume that the binary tree is sorted, i.e., it is a binary search tree.

```
template <class T>
BinaryNode<T>* BinaryTree<T>::find(BinaryNode<T>* subRoot, const T& x) const
{
```

Write a templated C++ class called BinaryNode which represents a node in a binary. Your class should contain all of the necessary data members for a node in a binary tree. (*Hint: Consider the link class from the Chain implementation*)

Recall that in class we used a map to represent a sparse vector. Suppose that we wished to use the map class to represent a sparse matrix. How could this be done? Give an example by creating an object called sMatrix that could represent a sparse matrix with only one non-zero value: sMatrix[52333][3] = 5.821.